

LMG640/670

Precision Power Analyzer



[Power Analysis] With



Two Bandwidths Simultaneously

Single-shot results for narrowband, broadband & harmonics measurements

LMG640/670 – powerful, convenient, flexible





Modular with up to seven power channels





Measurement Channels

Setting the bar in power analysis

For more than three decades, ZES ZIMMER has been focused solely on high-precision power measurement technology – so we know there is more to it than simply measuring current and voltage. Anyone who has tried to use generic data acquisition systems for power measurement will have rapidly run up against their limitations. What is the situation with common-mode rejection? Is the result still reliable for power factors in the range of 0.01? Is the earth capacitance low enough to avoid interference by leakage currents? In which frequency ranges does the manufacturer guarantee the stated measuring accuracy? It quickly becomes clear that only a device designed specifically for power measurement can really satisfy these high requirements. The LMG600 from ZES ZIMMER stands out in the market for its extreme reliability, best-in-class accuracy, and maximum frequency range – the ideal prerequisites for excellent results.

The right channel combination for every application

Power analyzers are available in different accuracy classes, to allow the user to choose the right tool for the job at hand. After all, not all applications require maximum precision; often lower resolution and frequency range are sufficient. Unfortunately, not all measuring applications exhibit this distinction. It is very well possible, for instance, to have need for different frequency ranges and accuracy levels at different points in the same measurement configuration. This is why the LMG600 offers three different channel types, which can be combined in the same chassis without problems to ensure that you always have a measuring device tailored to your needs for your particular application, without having to accept trade-offs in accuracy or take a sledgehammer to crack a nut, if a lower priced solution could have served your purposes equally well.



Measuring in two bandwidths at the same time, thanks to DualPath - no compromises, no doubts

On conventional power analyzers, a signal first undergoes analog conditioning, followed by optional anti-aliasing filters, to then be fed into an A/D converter. The resulting signal can afterwards be used for the calculation of cycle-based RMS values. Alternatively it can serve as the base for an FFT or further digital filtering. Due to the limitation to a single A/D converter, there are inherently some downsides to be factored in with conventional devices. If measurements are carried out with filters active, in order to avoid aliasing with FFTs, then the wide-band values are lost. With the filters switched off, strictly speaking, FFTs should not be used. If, in spite of this, FFTs are used without an anti-aliasing filter for measurements across the full frequency range, then the quality of the calculated values is questionable. An aliasing error of 50 %, for instance, is easily detected, however a deviation of 0.5 % could go unnoticed. Ultimately, when you alternate filtered and non-filtered measurements, the validity of the results is equally in question, as this involves the assumption that the signal does not change over time, which is in practice hardly ever the case. In addition, this procedure is especially time consuming.



In the end, all of the measurement methods presented are merely unsatisfactory compromises. This is why ZES ZIMMER has fundamentally redesigned signal processing and developed the DualPath architecture. The analog side is the same as in conventional measuring devices, however the subsequent digital processing has been revolutionized. The LMG600 is the first power analyzer to have two A/D converters in two independent signal paths for each current and voltage channel. One, for the filterless measurement of the wideband signal, and another, for the narrowband signal at the output of the anti-aliasing filter. The parallel processing of the digitized sample values gives the user access to both measurements of the same signal, without risking aliasing effects. This unique procedure avoids all of the downsides of previous approaches and guarantees the most precise result in the shortest time possible.



Gapless measurement

In the course of stricter monitoring of the consumption and efficiency of electrical devices, new standards and procedures are continuously being introduced (e.g. SPECpower_ssj2008, IEC 62301, EN 50564), in order to enable an impartial comparison of products from different manufacturers. Be it an office computer, server or household appliance, the same principle applies: the procedure always requires long term analysis of the power consumption, taking into account all relevant operating conditions. The differences between minimum load - e.g. in standby - and full load can be of a significant magnitude, which makes precise measurement very challenging (see also application report no. 102 "Measurement of standby power and energy efficiency" at www.zes.com). Some of the measurements required must be performed over several hours, yet without gaps. By selecting a sufficiently wide measurement range, changing ranges and the inevitably associated losses in data can be avoided. The high basic accuracy of the LMG600 ensures precise measurement results, even near the lower limit of a range.

Precise measurements thanks to minimal delay differences

The fast-switching semiconductors used in modern frequency converters to improve efficiency produce extremely steep voltage edges. The resulting capacitive currents put strain on the bearings and the insulation of the motors – this can lead to premature failure.

Motor filters (e.g. dU/dt filters) attenuate the steep voltage gradient, although they generate power losses themselves due to the transient oscillation with the filter's own frequencies (typically > 100 kHz). The broad frequency range and the minimal delay between current and voltage on LMG600's allow extremely precise power loss measurements on the filters at these frequencies, including longitudinal measurements at low power factors. This also applies to power measurements with high frequency ranges of up to 10 MHz, which require the current and voltage channels to be designed for the smallest delay differences. On the LMG600 the offset is less than 3 ns, corresponding to a phase error <1 µrad at 50 Hz. This makes the devices best suited to measure the power losses at low phase angles for transformers, chokes, capacitors and ultrasonic generators. No additional options or adjustments are required; the LMG600 is already fully capable of this measurement task with the standard factory settings. Usually current and voltage transducers are used for measurements on high-power circuits. The phase angle of these transducers can be corrected to improve measurement accuracy.

Exact measurements without limits

Although the LMG600 offers unmatched dynamic range, both for voltage and current, there are always applications with extraordinary requirements in terms of measurement ranges. Whether you are dealing with currents of several hundred amps or voltages of several kilovolts, ZES ZIMMER has the right solution at the ready. We offer a wide range of current and voltage sensors, which work perfectly in unison with the LMG600 precision power analyzer and extend the measurement ranges of the device by the required amount. The sensors of our Plug 'n' Measure series are equipped with a bus system, which enables automatic configuration of the LMG600. This allows for all of the important parameters, such as the precise scaling factor, the delay compensation variable, the last calibration date, and the sensor type, to be read automatically by the power analyzer and taken into account during measurements. Moreover, the sensors are actively supplied with power by the LMG600, separate power supplies are no longer required.

With Plug 'n' Measure there is no need for fine tuning by the user to achieve the best possible results. From the user's perspective, there is no difference between direct and sensor-supported measurements. Of course, other commercially available sensors can also be used with the LMG600.



Sensor Type PCT

Powerful interfaces

In addition to the GUI and the connection to the device under test itself, the exchange of data with the existing computer and software environment is of primary importance in determining how well the instrument is able to perform its intended task. Only with seamless integration into the overall system can the full power of the instrument be harnessed by the user. The high sampling rate of the LMG600 inevitably creates a large amount of data. Therefore we have ensured, by using the right system architecture, that the measured data can be transmitted via the interfaces at a high through put rate. Even high-resolution measurements of all important parameters such as current, voltage, active power, et cetera over a period of several minutes can be rapidly transferred to a connected computer. In order to cope with the requirements of a wide array of different applications, a range of ports is available. In addition to a serial port and Gigabit Ethernet, a slot is available for USB 2.0; the device can also optionally be equipped with a VGA/DVI output for connecting an external monitor or projector. Two more slots can be retrofitted for future interface standards. By using the integrated sync interface, it is possible to precisely synchronize multiple LMG600's with one another. This makes it possible to have a common time base for measurements involving multiple LMG600's on the same system, or the mutual connection and control of an LMG600 by oscilloscopes or waveform generators. Thanks to its internal HDD, the LMG600 provides the option to store measured values, settings, user-defined measurement variables, or graphs for later use, even without having a PC connected. When it comes to storage capacity, the customer has several options available. The firmware of the LMG600 can be quickly and easily brought up to date via USB.



Process signal interface

It is often necessary to take further measurements in addition to electrical parameters to be able to make a meaningful overall statement on the performance and efficiency of the device being tested. Hence, it is vital to be able to perfectly synchronize these measured values with the RMS values calculated by the LMG600, in order to establish reliable timing between electrical and mechanical events. A typical application is the analysis of electrical drive systems, where torque and speed must be measured and reconciled with the electrical parameters. Conversely, it may also be necessary for the power analyzer to output results for further processing in analog form, or to trigger switching operations depending on measured variables or derived values. In order to be equipped for all of these potential requirements, the LMG600 offers a multitude of different input/output features for analog and digital signals.

2 fast, synchronized analog inputs (ca. 150 kS/s)
8 analog inputs
8 switching inputs (ca. 150 kS/s)
2 torque-/speed-/ frequency inputs
32 analog outputs
8 switching outputs

Star-to-delta conversion

In three-phase three-line systems, only the line-to-line voltages V_{12} , V_{23} , V_{31} and the line currents I_1 , I_2 , I_3 are accessible for measurement. With the star-to-delta conversion option, the line-to-line voltages can be converted to non-accessible phase voltages and the related active power can be determined. Likewise the line currents can be converted into "linked" currents. From these calculated values it is possible to derive all other variables, such as harmonics. Distortions and imbalances of the grid or consumers are properly taken into account. This makes the use of an external, artificial neutral point superfluous;





3-phase 3-wire system: measuring phase-to-phase voltage and line currents

Easy to use - with or without touchscreen

To ensure that the LMG600 can be used in all conditions, particular attention has been paid to universal usability. All display modes and setting options can be operated both by the touchscreen or the keypad, without exception. The optimized design consistently links the keypad to the associated views and setting options on the screen. To use the instrument effectively requires almost no familiarization. The graphical user interface directs the user without detours to the required values. Be it RMS of voltage or current, associated harmonics or cumulative values, these are usually only a single press of a button away. In addition, user-defined views allow to group individually measured values, so that all the parameters are always available at a glance. This ergonomic way of operation and the associated time savings contribute directly to the productive use of the LMG600. The eight context-specific double softkeys to the right of the display, whose function always corresponds to their on-screen counterparts on the right-hand side, are especially important for ease-ofuse. One can determine the function assigned to a given softkey at a glance. The double softkey design enables the respective parameter to be rapidly configurable; switching through views that are not relevant is no longer necessary. Should there be questions as to function and control while operating the device, the relevant sections of the manual can be displayed at any time.



Simultaneous measurement of narrow and broadband values



Superimposed help text from manual



Display of measured RMS values



Display of sampling values of 8 signals in two scopes

Everything important just a click away

AULT Group 1	Broup 2 Group 3 Group 4 5	iums	Displ	31	DEFAULT Group 1 Grou	p 2 Group 3 Group 4 Sun	ns		Displa
	(All Channels)	(All Channels)	Harmo	nice					Norm
		h 18.4107 HZ	A Transf	²⁰¹¹					A Transfo
			Phase	- cn 🚍					Phase-
U1	0.020	U2	U3 12 V	NCT	p 1 9493 W	1 8981 W		5 79625 W	Bandwis
0.030 V	0.021	V 0.0	09 V	ven/					Wide (*
0.010 V 0.025 V	0.012	: V 0.0	40 V	<u> </u>		0.24407 ind	0.25470 ind	0.24869	Few
47.775 V 0.045 V	47.734	IV 47.7	53 V 16 V						
			23 V						
0.0 m Grp. 188	6rs. 2 cu 10-40 rs		a Gravita	-	Cycle 200.0 ms 6rp. 158	Grs. 2 GM		p. 318t Grgs. 418t	
acal A 1-230-0 1	2-250.5 V 500.5 million 1-250.5	V 4 200.0 met	A SA S.0 W		Chi Local 🖄 1 232-0-1	1 2 150.0 V 10 100.0 W 1 1 100.0 V	4 - 192.0	0.0 V 5.0 ml 6405.0 ml	-
		1					•		
							Click on the	<phase-ch> sof</phase-ch>	tkey:
							measured vo	alues for all chai	nnels oi
		Click on softkev	<pre>v <display>: toggling</display></pre>	7			linkeu vulue	s in a group	
		between RMS vo	alues and harmonics						
			POWER	Group 1 Group 2 Gr	roup 3 Group 4 Sum	s Efficiency			Disptay
					C	roup 1			Normal
					U	ioup i			Transform
			P	12.1070	W C				
Fixed I	Interval interval 200.0 ms	() () () () () () () () () () () () () (2						Group
Har	m1 7 8	9 min	S	25.6706	5 VA				
Har	m 2 m 3 4 5	6 .	2						Bandwidt Narrow (
Har	m4 1 2	3	0	22.6363	3 var				Values
Sci	ope 0 .	ms							Few
Enter		Cancel	PF	0.47163	3				
AND THE REAL PROPERTY OF	an an Anna 19 - Na 19 - Martin Martin, an Anna an	1 100 100 100 100 100 100 100 100 100 1							
			fovele	49.997	7 Hz				
	Clister of C		·cycle	6 160 - 64	3 100		Core 2 CB	for ARI	-
	Click on C	ycle: <i>Lonfiguratioi</i> imo or roforonco	7 Cycle 500.0 m	50.00 Hz 18 41	2 UAI H2 1-0 V	250.0.4	1.549 kHz		
	Of Cycle L	ine or rejerence	Ctrl Local	0 300.0 mA	500.0 m	4 600.0 nA	5.0 mA	6P 5.0 nA	<u> </u>
			Click on the group	: configuration	Click on the	level indicator: (configuration		
			of activation, syn	chronization,	of channel-s	pecific measure	ment ranges		
			filters, etc.		and sensor s	ettings			

	Signal	Harm	onics		Sync	Signal
Wiring Processing Signal Coupling	Direct Dual Path AC+DC	Harmonics Phase Angle Ref. Spect. Mode	Custom U Harmonics	f _{oste} Source Bandwidth	49.9991 Hz U1 Narrow	Wring Direct Processing Dual Path
Narrow Filter Wide Filter	LP: Bessel, 8,0 KHz HP: RC, 1,0 Hz LP: 150,0 KHz	Interharm. Number Mode Max. Number	D Custom -1	Level Hysteresis Filter	0.0 % 2.0 % LP: 15.0 kHz HP: Off	Signal Coupling ACHOC Filter
				Demod	Uff Enter Trigger View	

Auto Range <mark>(Auto Auto Auto)</mark> Jack U+ U+	Channel
Jack Un Un	
	2
Sensor Default Default Default	Select (/L
Range 250.0 V 250.0 V 250.0 V	
	Auto Rang Auto
	4
Auto Range Auto Auto Auto	JSEX U*
Jack I* I*	Sentor
Sensor Default Default Default	Default
Range 600.0 mA 600.0 mA 600.0 mA	Parge
	250.0 V

Clear visualization of measurements thanks to groups

In order to properly illustrate the functional relations between physical measurement channels, the power measurement channels (P-channels) can be organized into so-called groups, which appear almost as virtual measurement channels or virtual devices in addition to the physical channels. The logical grouping of the P-channels is dependent on the number of wires and phases of the electrical system being analyzed. Thanks to the flexibility of the LMG600, it is possible to model even unusual and rarely seen configurations, such as split-phase systems and four-phase or multiphase systems, both simply and reliably. The only requirement is that all of the channels within a group have the same basic frequency and are of the same type (A, B, C). This will avoid subtle errors, which arise due to the different technical properties of the different channel types. One benefit of creating groups is that it makes configuring the device easier, since filter settings (for example) affecting all channels in the group only have to be configured once. In addition, derived values, such as active, apparent or idle power are calculated across all channels in the group. While grouping specifies how the channels are combined logically, the wiring dictates how the inputs of the measuring device are connected to the measuring circuit, i.e. whether it is a star-to-delta circuit or whether there are neutral wires, etc. The wiring defines how the measured signals are interpreted by the device.



Example: measurement on frequency converter

Group I measures the input power in an Aron circuit. C-channels are usually sufficient.

To determine the output power, Group II measures the voltages on the delta side and the currents on the star side. A-channels are recommended for this. Using another singlechannel group, the DC intermediate circuit can also be measured. A-channels would also be indicated here.



Logical grouping of channels for different points of measurement in the LMG600 configuration menu

Electrical drive systems

Frequency converter

DC

AC

3)

A/B channel

More than half of the electrical energy generated worldwide is converted to mechanical motion, and the importance of electric powertrains for transport of goods and people is growing steadily. While outdated speed controllers are afflicted with losses of up to 40%, modern, frequency-controlled systems can achieve efficiency levels of over 95%. These frequency converters use pulse

AC

2-4

1)

DC.

2)

A/B channel

width modulation to control the speed of the motor with hardly any losses. The objective is to optimally adjust the converter and motor to one another, in order to achieve the best overall efficiency. Measuring the input power, the intermediate circuit, and the output power of the converter as well as the mechanical power of the motor simultaneously is anything but trivial. In addition to

Μ

4)

M, Mn

the integration of sensor technology (wideband sensors for high currents, high-voltage dividers, precise speed and torque transmitters), the instrument must meet the challenge of measuring the very steep-flanked signals at the converter output. This environment is often described as harsh, not merely from an EMC point of view.

Determining the efficiency of an electric drive system

- 1) Input of the converter: C-channels are usually sufficient for this.
- 2) DC intermediate circuit: depending on the required level of precision, A or B-channels are required, as the DC
- intermediate circuit exhibits significant residual ripple under certain circumstances.
- 3) Converter output: depending on the required level of precision, A or B-channels only are to be used.
- 4) Measurement of mechanical quantities synchronously to 1) 2) 3) 4) up to 150 kS/s via process interface

and another one on a filtered signal to determine the power at certain frequencies, resp. a subsequent FFT analysis to measure the harmonic spectrum. This procedure is very time-consuming, yet it cannot guarantee that the conditions present during the initial measurement still prevail during the repetition.

The innovative DualPath architecture of the LMG600 provides all of the required results simultaneously in a single measurement, with maximum precision, and the widest frequency range on the market – free from aliasing effects.





Of course the key question in the analysis of electrical drive systems is: which part of the electrical energy at the converter output relates to the torque-relevant fundamental frequency of the motor, and which part to the remaining frequency range, particularly the harmonic spectrum? To give an accurate answer, it has long been necessary to perform two separate measurements: one without filters to establish the wideband power,

Switched-mode power supplies

Already years ago, advances in power electronics have caused relatively large and heavy transformer power supplies to be replaced by smaller, lighter and more efficient switched mode power supplies. Today those can be found in practically all grid-powered electrical devices. While avoiding many of the downsides of their predecessors, they also bring new challenges: for one, the conducted emissions due to harmonics are not insignificant and must be limited by standards (EN61000-3-2, EN61000-3-12). Secondly, the high switching frequencies of up to several hundred kilohertz can lead to problems with electromagnetic compatibility, both on the grid side and on the consumers' part. The role of power measurement technology is to support the manufacturer in optimizing their products.

CHALLENGES

- Gapless, standards-compliant measurement of harmonics
- High frequency range for analysis of conditions at pulse frequencies >300 kHz
- Quick and gapless sampling for measuring steep switching flanks
- \cdot Reliable measurement even at power factors λ < 0.01



Solid & laminated magnetic cores

Under the influence of changing fields, the ferromagnetic components of an electrical machine are subject to losses due to continuous remagnetization and eddy currents, which are ultimately converted into heat or vibrations.

The total losses are frequency-dependent and should be minimized as far as possible, as they

have a significant effect (for example) on the range of the batteries in electric vehicles. The core power loss can be calculated directly from the excitation current of a test winding and the magnetization voltage of a sensor winding. The magnetic flux density in the core material can be derived from the rectified value of the voltage induced in the sensor winding. The magnetic field strength is proportional to the current flowing in the test winding.

While the high-frequency currents in solid cores can be measured directly, the high amp values occuring in laminated cores usually demand high-precision transducers.



Conformance testing for the aerospace industry

Particularly in the aerospace industry, electromagnetic compatibility between installed systems is of existential importance. For this reason, industry directives such as ABD0100.1.8 set limits on harmonic currents up to the range of 150 kHz. These harmonics can be analyzed using the LMG600. This can either be accomplished using the built-in harmonics analysis, or alternatively in any level of detail via off-line analysis of sample values using external software.



Lighting technology

In an effort to reduce energy consumption, light bulbs are being replaced with ever more efficient light sources all around the world. While on the consumer end all that is required is to insert a new product into the existing fitting, the differences on the electrical level are considerable – in contrast to conventional bulbs, LED lights and compact fluorescent lights ("low-energy light-bulbs") are controlled by special electronic ballasts. Some of these ballasts work with switching frequencies of up to 200 kHz and produce signal distortions at frequencies of up to 1 MHz. The manufacturers are required first and foremost to prevent damaging circuit feedback, and secondly, to en-

sure optimum service life for their products. To achieve the aforementioned objectives, often a controlled warm start is performed, whose proper execution has to be verified by making appropriate measurements.

CHALLENGES

- Broad frequency range of the measurement, hand-in-hand with a high level of precision
- Verification of standby power of ballasts even for $\lambda < 0.01$
- Minimal earth capacitance to avoid leakage currents during the
 measurement



CE compliance testing for harmonics and flicker

Electrical equipment, systems and devices must satisfy the directives and ordinances of the EU on the permitted level of electromagnetic emissions and immunity to electromagnetic effects, if they are put on the market inside the European Union (EU). Two different types of grid emissions are tested: harmonics and flicker. Any electrical device with a non-linear load characteristic produces current harmonics. Due to the impedance of the grid, these cause drops in voltage and resulting distortions. In addition, certain devices (e.g. continuous-flow heaters, heating furnaces, et cetera) control their power consumption by abruptly switching on and off, which destabilizes the voltage level due to the grid impedance. This produces fluctuations in voltage, which trigger variations in brightness in the electric lighting ("flicker"). In combination with a suitable AC source and reference impedance, the LMG600 is the tool of choice for the qualified assessment of harmonics and flicker. The LMG Test Suite (see accessories) is providing a user-friendly software solution for this, which turns performing conformity tests for electromagnetic compatibility into child's play.



Technical Data (Summary)

A channel		± (% of measured value + % of maximum peak value)												
Accuracy	DC	0.05 Hz 45 Hz 65 Hz 3 kHz	45 Hz 65 Hz	3 kHz 10 kHz	10 kHz 50 kHz	50 kHz 100 kHz	100 kHz 500 kHz	500 kHz1 MHz	1 MHz 2 MHz	2 MHz 10 MHz				
Voltage U*	0.02+0.08	0.015+0.03	0.01+0.02	0.03+0.06	0.2	0.2+0.4		0.5+1.0	f/1MHz*1.5	+ f/1 MHz*1.5				
Voltage U _{SENSOR}	0.02+0.08	0.015+0.03	0.01+0.02	0.03+0.06	0.2+0.4		0.4+0.8	0.4+0.8	f/1MHz*0.7	+ f/1 MHz*1.5				
Current I* 5 mA5 A	0.02+0.1	0.015+0.03	0.01+0.02	0.03+0.06	0.2+0.4		0.5+1.0	0.5+1.0	f/1 MHz*1.0 + f/1 MHz*2.0	-				
Current I* 10 A32 A	0.02+0.1 ¹⁾	0.015+0.03 ³⁾	0.01+0.023)	0.1+0.2 ³⁾	0.3+0.6 ³⁾ f/100 kHz*0.8 + f		+ f/100 kHz*1.2 ³⁾	-	-	-				
Current I _{sensor}	0.02+0.08	0.015+0.03	0.01+0.02	0.03+0.06	0.2+0.4		0.4+0.8	0.4+0.8	f/1MHz*0.7	+ f/1 MHz*1.5				
Power U*/I* 5mA5A	0.032+0.09	0.024+0.03	0.015+0.01	0.048+0.06	0.32	2+0.4	0.8+1.0	0.8+1.0	f/1MHz*2.0+ f/1MHz*1.8	-				
Power U*/ I* 10 A32 A	0.032+0.09 ²⁾	0.024+0.034)	0.015+0.014)	0.104+0.134)	0.4+0.54)	f/100 kHz*0.8 + f/100 kHz*0.8 ⁴⁾	f/100 kHz*1.0 + f/100 kHz*1.1 ⁴⁾	-	-	-				
Power U*/ I_{sensor}	0.032+0.08	0.024+0.03	0.015+0.01	0.048+0.06	0.32	!+0.4	0.72+0.9	0.72+0.9	f/1MHz*1.8	+f/1MHz*1.5				
Power U _{SENSOR} /I* 5 mA5 A	0.032+0.09	0.024+0.03	0.015+0.01	0.048+0.06	0.32	!+0.4	0.72+0.9	0.72+0.9	f/1MHz*1.4+ f/1MHz*1.8	-				
Power U _{SENSOR} / I* 10 A32 A	0.032+0.09 ²⁾	0.024+0.034)	0.015+0.014)	0.104+0.134)	0.4+0.5 ⁴⁾	0.4+0.5 ⁴⁾ f/100 kHz*0.8 + f/100 kHz*0.8 ⁴⁾		-	-	-				
$PowerU_{_{SENSOR}}/\mathrm{I}_{_{SENSOR}}$	0.032+0.08	0.024+0.03	0.015+0.01	0.048+0.06	0.32	?+0.4	0.64+0.8	0.64+0.8	f/1MHz*1.1	+ f/1 MHz*1.5				

B channel Accuracy		<pre>± (% of measured value + % of maximum peak value)</pre>											
	DC	0,05 Hz 45 Hz 65 Hz 1 kHz	45 Hz 65 Hz	1 kHz 5 kHz	5 kHz 20 kHz	20 kHz 100 kHz	100 kHz 500 kHz						
Voltage U*	0.1+0.1	0.1+0.1	0.03+0.03	0.2+0.2	0.3+0.4	0.4+0.8	f/100 kHz*0.8 + f/100 kHz*1.2						
Current I* 5 mA5 A Current I _{SENSOR}	0.1+0.1	0.1+0.1	0.03+0.03	0.2+0.2	0.3+0.4	0.4+0.8	f/100 kHz*0.8 + f/100 kHz*1.2						
Current I* 10 A32 A	0.1+0.11)	0.1+0.1 ³⁾	0.03+0.03 ³⁾	0.2+0.2 ³⁾	0.6+1.2 ³⁾	1.5+1.5 ³⁾	f/100 kHz*2.0 + f/100 kHz*2.0 ³⁾						
Power U*/ I* 5 mA5 A Power U*/ I _{SENSOR}	0.16+0.1	0.16+0.1	0.05+0.02	0.32+0.2	0.48+0.4	0.64+0.8	f/100 kHz*1.28 + f/100 kHz*1.2						
Power U*/ I* 10 A32 A	0.16+0.12)	0.16+0.14)	0.05+0.024)	0.32+0.24)	0.72+0.84)	1.52+1.154)	f/100kHz*2.24+ f/100kHz*1.64)						

C channel			± (% of measu	red value + % of maxim	um peak value)		
Accuracy	DC 0,05 Hz 45 Hz 65 Hz 200 Hz		45 Hz 65 Hz	200 Hz 500 Hz	500 Hz 1 kHz	1 kHz 2 kHz	2 kHz 10 kHz
Voltage U*	0.1+0.1	0.02+0.05	.05 0.02+0.02 0.05+0.05		0.2+0.1	1.0+0.5	f/1kHz*1.0+ f/1kHz*1.0
Current I*	0.1+0.1 ¹⁾	0.02+0.053)	0.02+0.02 ³) 0.05+0.05 ³)		0.2+0.1 ³⁾	0.2+0.1 ³⁾ 1.0+0.5 ³⁾	
Current I _{SENSOR}	0.1+0.1	0.02+0.05	0.02+0.02	0.05+0.05	0.2+0.1	1.0+0.5	f/1kHz*1.0+ f/1kHz*1.0
Power	0.16+0.1 ²⁾	0.032+0.054)	0.03+0.014)	0.08+0.054)	0.32+0.14)	1.6+0.54)	f/1 kHz*1.6 + f/1 kHz*1.04)
Accuracies valid for:	1. Sinusoidal vo 2. Ambient tem 3. Warm-up tim 4. The maximur peak valu	oltages and currents perature (23±3) °C e 1 h n peak value for power is th ue for voltage and the max	ne product of the maximum imum peak value for curren	ı ıt.	5. 0 ≤ λ ≤ 1 (powe 6. Current and voltz 10% 110% of r 7. Adjustment carri 8. Calibration inter	r factor) age nominal value ed out at 23 °C val 12 months	
Other values		All other values are cal	lculated from current, volta (e.g. S	age and power. Accuracy = I * U, $\Delta S / S = \Delta I / I + A$	resp. error limits are derived ∆U / U).	according to context	

^{1) 2) 3) 4)} only valid in range 10 ... 32 A:

¹⁾ additional uncertainty $\pm \frac{50\,\mu A}{A^2} * I_{trms^2}$ ²⁾ additional uncertainty $\pm \frac{50\,\mu A}{A^2} * I_{trms^2} * U_{trms}$ ³⁾ additional uncertainty $\pm \frac{30\,\mu A}{A^2} * I_{trms^2}$ ⁴⁾ additional uncertainty $\pm \frac{30\,\mu A}{A^2} * I_{trms^2} * U_{trms^2} *$

Voltage measuring ranges U*															
Nominal value (V)	3		6	12.5	25		60	130	2	250	400	6	00	1000	
Max. trms value (V)	3.3		6.6	13.8	27.5		66	136	2	270	440	6	50	1000	
Max. peak value (V)	6 12 25		50		100	200	4	00	800	16	00	3200			
Overload protection		1000V + 10% permanently, 1500V for 1 s													
Input impedance							4.59 M	Ω, 3 pF							
Earth capacitance		< 90 pF													
Current measuring ranges I*															
Nominal value (A)	0.005	0.01	0.02	0.04	0.08	0.15	0.3	0.6	1.2	2.5	5	10	20	32	
Max. trms value (A)	0.0055	0.011	0.022	0.044	0.088	0.165	0.33	0.66	1.32	2.75	5.5	11	22	32	
Max. peak value (A)	0.014	0.014 0.028 0.056 0.112 0.224 0.469 0.938 1.875 3.75 7.5 15 30								60	120				
Input impedance	ca. 2.2	2Ω		ca. 600 mΩ	2		ca. 80 mΩ			ca.20mΩ			ca. 10	mΩ	
Overload protection permanent (A)				LMG in op	eration 10 A						LMG in c	peration 32 <i>1</i>			
Overload protection short-time (A)							150 A fo	or 10 ms							
Earth capacitance							< 9	0 pF							
Sensor inputs U _{SENSOR} , I _{SENSOR}															
Nominal value (V)	0.03		0.06		0.12	().25	0.5		1		2		4	
Max. trms value (V)	0.033 0.066 0.132		0	.275	0.55	5	1.1		2.2		4.4				
Max. peak value (V)	0.0977		0.1953		0.3906	0.	7813	1.56	3	3.125 6.25		12.5			
Overload protection						100	V permaner	itly, 250 V fo	r 1s						
Input impedance		100 kΩ, 34 pF													
Earth capacitance							< 9	OpF							
Isolation	All current a Max. 1000 V	nd voltag / CAT III r	e inputs are esp. 600 V /	isolated aga CAT IV	inst each oth	er, against	remaining e	lectronics ar	ıd against e	arth.					
Synchronization	Measuremen with configu electronic lo	ts are syn rable filte ads.	chronized or rs. Therefor	n the signal e readings a	period. The p re very stable	eriod is det , especially	ermined bas with PWM co	ed on "line", ontrolled free	"external", quency conv	u(t) or i(t), erters and a	, in combin amplitude	ation modulated			
Scope function	Graphical dis	splay of sa	mple values	over time i	1 two scopes (with 8 signa	Ils each								
Plot function	Two time (tre	end-) diag	rams of max	<. 8 paramet	ers, max. res	olution 30 r	ns								
External graphics interface (L6-OPT-DVI)	VGA/DVI inte	erface for	external scr	een output											
Process signal interface (L6-OPT-PSI)	2 fast analog 8 analog inp 32 analog ou 8 switching o 8 switching i Speed-/torq	2 fast analog inputs (150 kS/s, 16 bit, BNC) 3 analog inputs (100 S/s, 16 bit, D-Sub:DE-09) 32 analog outputs (output per cycle, 14 bit, D-Sub: DA-15 & DB-25) 8 switching outputs (6 switches with 2 connections each and 2 switching outputs with common negative, D-Sub: DB-25) 8 switching inputs (150 kS / s, in two groups 4 inputs each with common ground, D-Sub: DB-25) Speed-/torque-/frequency inputs (150 kS/s, D-Sub: DA-15)													
Star-delta conversion (L6-OPT-SDC)	Conversion of	of line volt	ages to pha	se voltages	and computa	tion of resu	lting active	power							
Harmonics at device level (L6-OPT-HRM)	Harmonics a	nd interha	rmonics up	to 2,000th o	rder										
Flicker (L6-OPT-FLK)	According to	EN 61000	-4-15												
LMG Remote	LMG600 expa	ansion so	tware, basi	c module for	remote conf	guration a	nd operation	n via PC							
L60-TEST-CE61K	LMG600 soft	ware for o	onformity t	ests accordi	ng to EN6100) for harmo	nics and flic	ker							
Miscellaneous Dimensions Weight Protection class Electromagnetic compatibility Temperature Climatic category Line input	LMG670: Tab LMG640: Tab Depending o EN 61010 (IE EN 61326 O 40 °C (o Normal envin 100 230 V	le-top ver le-top ver n installe C 61010, V peration) ronmenta , 47 63	sion for 7 sl sion for 4 sl d options: n /DE 0411), p / -20 50 conditions Hz, max. 40	ots: (WxHxI ots: (WxHxI nax. 18.5 kg rotection cl °C (storage according t 0 W for LMG)) 433 mm x 1)) 284 mm x 1 for LMG670, 1 ass I / IP20 ir) o EN 61010 570, max. 200	77 mm x 59 77 mm x 59 nax. 15.5 k accordanc)W vor LMG	0 mm, 19″ vu 0 mm, 19″ vu g for LMG64 e with EN 60 640	ersion for 7 s ersion for 4 s 0 1529	lots: (WxHx lots: (WxHx	D) 84 HP x 4 D) 84 HP x 4	4 RU x 590 4 RU x 590	mm mm			

Accessories program (excerpt)

Current sensors									
Туре		Rin	ig-type transduc	ers		Current	clamps	Flexible	Shunt
			DANIJENSE			<u> </u>	0	0.	100
Name	РСТ	L60-Hall	DS5000	LMG-Z601	LMG-Z500	LMG-Z406, L45-Z10/16	L45-Z26	L60-Flex	LMG-SH (-P)
Signal type		AC+DC			AC	AC	AC+DC	AC	AC+DC
Current ranges	602000 A _{rms}	502000 A _{rms}	605000 A _{rms}	100 A _{rms}	0.1 10 kA _{rms}	403 kA _{rms}	301 kA _{rms}	500 3 kA _{rms}	37mA0.6A _{rms}
Best accuracy	0.015%	0.3%	0.07%	0.15%	0.02%	0.1%	1.5%	2%	0.15%
Max. bandwidth	0 Hz1 MHz	0 Hz 150 kHz	0 Hz 10 kHz	30 Hz 1 MHz	5 Hz 15 kHz	2 Hz 50 kHz	0 Hz 2 kHz	10 Hz5 kHz	4565 Hz
Power supply by LMG600	Y	es	No	Not r	equired	Y	es	Not re	quired
Plug 'n' measure	Y	es	No		No		Yes		No



Breakout box				
Name	LMG-MAS	LMG-MAK1	BOB-CEE3-16	BOB-CEE3-32
Nominal voltage	250 V	300 V	230/	400 V
Category	CA	TIII	CA	TII
Safety standard	IEC / EN	161010-1	IEC / EN	61010-1
Socket for load connection	16 A 250 V CEE 7/4	10 A 250 V IEC 60320-C14	16 A 400 V 3L+N+PE, 6 h IEC 60309	32 A 400 V 3L+N+PE, 6 h IEC 60309

The Breakout Boxes enable access to the individual lines in a connector for measurement, and provides an easy and elegant way to take measurements on single and three-phase consumers.





© 2017 - ZES ZIMMER Electronic Systems GmbH - subject to technical changes, especially product improvements, at any time without prior notification.



Germany (headquarter) ZES ZIMMER Electronic Systems GmbH Tabaksmühlenweg 30 • D-61440 Oberursel info@zes.com • +49 6171 88832-0 www.zes.com United States (subsidiary) ZES ZIMMER Inc. 2580 Thornhills Ave. • Suite 114 Grand Rapids. • MI 49546 usa@zes.com • +1 760 550 9371